

§ 8.6 修正された Hamilton-Dirichlet の原理 2

(8.4.4)式で与えられる Hamilton-Dirichlet の原理において, 水と板との連続条件(8.4.5b)式を拘束して, w を消去すると

$$\begin{aligned}
 \Pi_{HD}^{*2}[\phi] &= \Pi_{KD}[w, \phi]_{w=\frac{1}{i\omega}\phi_z(x,y,0)} \\
 &= \frac{1}{2} \iint_R m \phi_z^2 dx dy \\
 &\quad - \frac{D}{2\omega^2} \iint_R \left[\left(\frac{\partial^2 \phi_z}{\partial x^2} \right)^2 + 2\nu \left(\frac{\partial^2 \phi_z}{\partial x^2} \right) \left(\frac{\partial^2 \phi_z}{\partial y^2} \right) + \left(\frac{\partial^2 \phi_z}{\partial y^2} \right)^2 + 2(1-\nu) \left(\frac{\partial^2 \phi_z}{\partial x \partial y} \right)^2 \right] dx dy \\
 &\quad - \frac{\rho g}{2\omega^2} \iint_R \phi_z^2 dx dy \\
 &\quad - \frac{\rho}{2} \iiint_{\Omega} \left[\left(\frac{\partial \phi}{\partial x} \right)^2 + \left(\frac{\partial \phi}{\partial y} \right)^2 + \left(\frac{\partial \phi}{\partial z} \right)^2 \right] dx dy dz \\
 &\quad + \rho \iint_R \phi \phi_z dx dy \\
 &\quad + \frac{\rho \omega^2}{2g} \iint_{S_F} \phi^2 dx dy \\
 &\quad + \rho \iint_{S_o} \bar{f}_o \phi dS \\
 &= \text{stationary} \\
 &\text{under } [K_{plate}^{*2}] + [M_{water}]
 \end{aligned}$$

(8.6.1)

を得る。ただし, $[M_{water}]$ は直接表に現れないので, 省略してもよい。この場合の $[K_{plate}^{*2}]$ は

$$M_x = -\frac{D}{i\omega} \left(\frac{\partial^2 \phi_z}{\partial x^2} + \nu \frac{\partial^2 \phi_z}{\partial y^2} \right) \quad \text{in } R \quad (8.6.2a)$$

$$M_y = -\frac{D}{i\omega} \left(\frac{\partial^2 \phi_z}{\partial y^2} + \nu \frac{\partial^2 \phi_z}{\partial x^2} \right) \quad \text{in } R \quad (8.6.2b)$$

$$M_{xy} = -(1-\nu) \frac{D}{i\omega} \frac{\partial^2 \phi_z}{\partial x \partial y} \quad \text{in } R \quad (8.6.2c)$$

である。

実際に, $\delta\Pi_{HD}^{*2} = 0$ を求めると

$$\begin{aligned}
0 &= \delta\Pi_{HD}^{*2} \\
&= \delta \left[\begin{aligned} &\frac{1}{2} \iint_R m \phi_z^2 dx dy \\ &-\frac{D}{2\omega^2} \iint_R \left[\left(\frac{\partial^2 \phi_z}{\partial x^2} \right)^2 + 2\nu \left(\frac{\partial^2 \phi_z}{\partial x^2} \right) \left(\frac{\partial^2 \phi_z}{\partial y^2} \right) + \left(\frac{\partial^2 \phi_z}{\partial y^2} \right)^2 \right. \\ &\quad \left. + 2(1-\nu) \left(\frac{\partial^2 \phi_z}{\partial x \partial y} \right)^2 \right] dx dy \\ &-\frac{\rho g}{2\omega^2} \iint_R \phi_z^2 dx dy \end{aligned} \right] \\
&\quad - \rho \iiint_{\Omega} \left(\frac{\partial \phi}{\partial x} \frac{\partial \delta \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{\partial \delta \phi}{\partial y} + \frac{\partial \phi}{\partial z} \frac{\partial \delta \phi}{\partial z} \right) dx dy dz \\
&\quad + \rho \iint_R (\delta \phi \phi_z + \phi \delta \phi_z) dx dy \\
&\quad + \frac{\rho \omega^2}{g} \iint_{S_F} \phi \delta \phi dx dy \\
&\quad + \rho \iint_{S_o} \bar{f}_o \delta \phi dS \\
&= \frac{1}{\omega^2} \iint_R \left[\begin{aligned} &i\omega \left(\frac{\partial^2 M_x}{\partial x^2} + 2 \frac{\partial^2 M_{xy}}{\partial x \partial y} + \frac{\partial^2 M_y}{\partial y^2} \right) \\ &+ m\omega^2 \phi_z + \rho\omega^2 \phi - \rho g \phi_z \end{aligned} \right] \delta w dx dy \\
&\quad - \frac{1}{\omega^2} \sum_{i=1}^N \int_{\Gamma_i} \left[-i\omega M_n \frac{\partial \delta \phi_z}{\partial n} + i\omega \left(Q_n + \frac{\partial M_{ns}}{\partial s} \right) \delta \phi_z \right] ds \\
&\quad + \frac{1}{\omega^2} \sum_{i=1}^N [i\omega M_{ns} \delta \phi_z]_{P_{i+}} - \frac{1}{\omega^2} \sum_{i=1}^N [i\omega M_{ns} \delta w]_{P_{i-}} \\
&\quad + \rho \iiint_{\Omega} \left(\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} \right) \delta \phi dx dy dz \\
&\quad - \rho \iint_R \left(\frac{\partial \phi}{\partial z} - \frac{\omega^2}{g} \phi \right) \delta \phi dx dy
\end{aligned}$$

$$\begin{aligned}
& -\rho \iint_{S_o} \frac{\partial \phi}{\partial n} \delta \phi dS \\
& -\rho \iint_{S_o} \left(\frac{\partial \phi}{\partial n} - \bar{f}_o \right) \delta \phi dS \quad (8.6.3)
\end{aligned}$$

となる。したがって、この変分問題の自然条件は

$$i\omega \left(\frac{\partial^2 M_x}{\partial x^2} + 2 \frac{\partial^2 M_{xy}}{\partial x \partial y} + \frac{\partial^2 M_y}{\partial y^2} \right) + m\omega^2 \phi_z + \rho\omega^2 \phi - \rho g \phi_z = 0 \quad \text{in } R \quad (8.6.4a)$$

$$i\omega M_n = 0 \quad \text{on } \Gamma_{D_i}, \quad (i=1,2,\dots,N) \quad (8.6.4b)$$

$$i\omega \left(Q_n + \frac{\partial M_{ns}}{\partial s} \right) = 0 \quad \text{on } \Gamma_{D_i}, \quad (i=1,2,\dots,N) \quad (8.6.4c)$$

$$i\omega M_{ns} = 0 \quad \text{at } P_{i\pm}, \quad (i=1,2,\dots,N) \quad (8.6.4d)$$

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} = 0 \quad \text{in } \Omega \quad (8.6.4e)$$

$$\frac{\partial \phi}{\partial z} = \frac{\omega^2}{g} \phi \quad \text{on } S_F \quad (8.6.4f)$$

$$\frac{\partial \phi}{\partial n} = 0 \quad \text{on } S_B \quad (8.6.4g)$$

$$\frac{\partial \phi}{\partial n} = \bar{f}_o \quad \text{on } S_o \quad (8.6.4h)$$

で与えられる。

(8.6.2)式を代入すると、(8.6.4a)式は

$$D \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right)^2 \phi_z - m\omega^2 \phi_z - \rho\omega^2 \phi + \rho g \phi_z = 0 \quad \text{in } R \quad (8.6.5)$$

と書ける[8,9]。

§ 8.7 参考文献

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